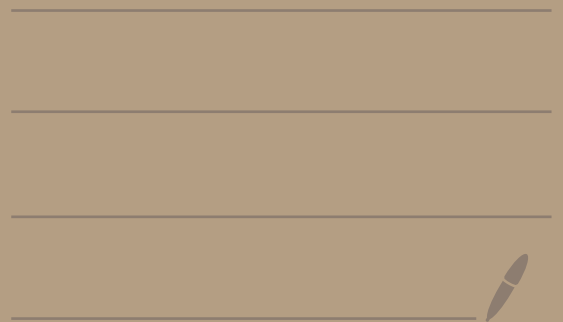
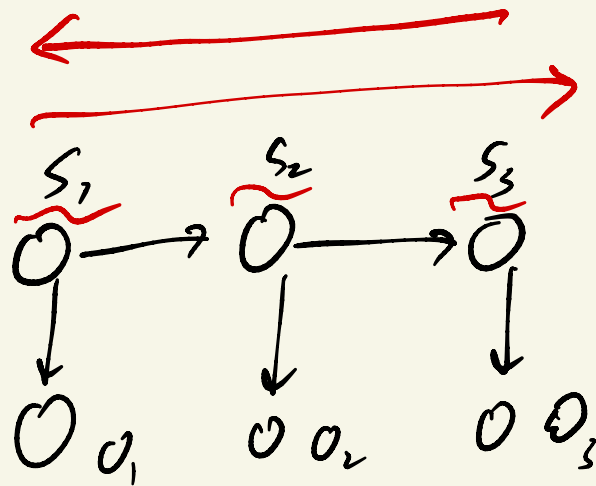
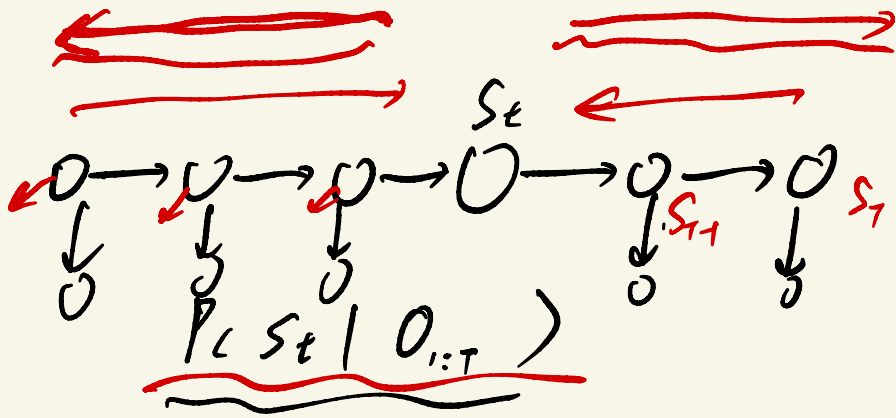


Lecture 22 GANs and RL

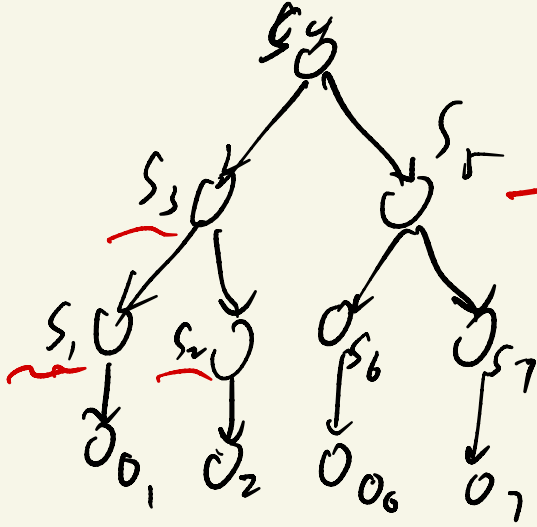




$$\begin{aligned}
 \underbrace{P(o_1, o_2, o_3)} &= \sum_{s_1} \sum_{s_2} \sum_{s_3} \underbrace{P(s_1)} \underbrace{P(o_1 | s_1)} \\
 &\quad \underbrace{P(s_2 | s_1)} \times \underbrace{P(s_3 | s_2)} \dots \\
 &= \sum_{s_2} \sum_{s_3} \left(\underbrace{\sum_{s_1} P(s_1) P(o_1 | s_1)}_{f(s_2)} \underbrace{P(s_2 | s_1)} \right) \times \dots
 \end{aligned}$$



$$S_{t-1} \rightarrow S_{t-2}$$



$P(o_1, o_2, o_6, o_7)$

inside-outside

deterministic: $x = G(z)$

distribution: $x = P(x; G(z))$

$$\bar{ELBO} = E_{z \sim q(z|x)} \log P(x|z) - KL(q(z|x) || P_z)$$

$$z \sim q(z|x)$$

$$\log P(x|z) \rightarrow -\infty$$

$$z \sim N(0, 1)$$

$$x = G(z)$$

$$P(x) = \int_z |P(z)| P(x|z)$$

$$G^{-1}(x)$$

$$x = G(z)$$

$$z = G^{-1}(x)$$



Flow generative model

$\arg \min C(Q)$

P_g

~~~~~

$P_g$

~

~~~~~

$C(Q)$

$KL \geq 0$

~~~~~

$KL=0$

$P_g = P_{data}$

$KL=0$

$$P_{\text{model}} \longrightarrow P_{\text{data}}$$

encoder  $\phi$      $\Theta$  decoder

$$\max_{\phi, \Theta} \bar{ELBO}$$

E stop:

$$q_{\phi}(z|x) \neq P_{\Theta}(z|x)$$

$\phi$  to convergence

$$q_{\phi}(z|x) \approx P_{\Theta}(z|x)$$

$$\max_{\Theta} \max_{\phi} ELBO$$

$$\max_{\phi, \Theta}$$



$P_g^*$  fixed

$$\text{MLE: } \mathbb{E}_{x \sim P_{\text{data}}} \log P_g(x)$$

// equivalence

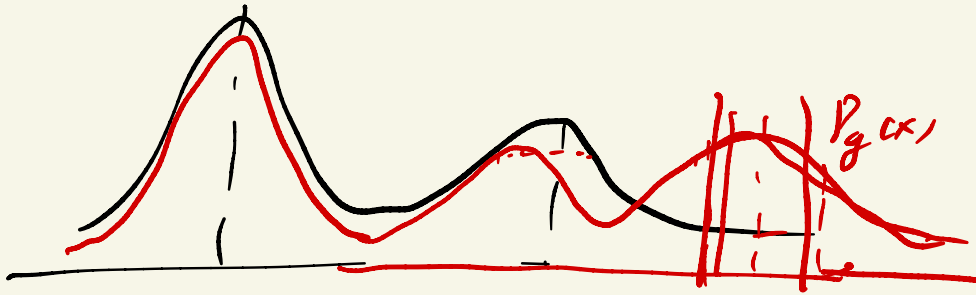
$$\min \underbrace{\text{KL}(P_{\text{data}} \parallel P_g)}_{\text{MLE}}$$

$$\text{KL}(P_g \parallel \frac{P_{\text{data}} + P_g^*}{2})$$

$$d(x, y) = \|x - y\|^2 \quad P_g = P_{data}$$

$$\cos(\vec{x}, \vec{y})$$

$$d(x, y) = d(y, x)$$



$$KLE(P \parallel Q) = \int P(x) \log P(x) - \int P(x) \log Q(x)$$

$$VAE: KL(P_{data} \parallel P_g) = \int P_{data} \log P_{data}(x)$$

$$- \int P_{data} \log P_g(x) \rightarrow \infty$$

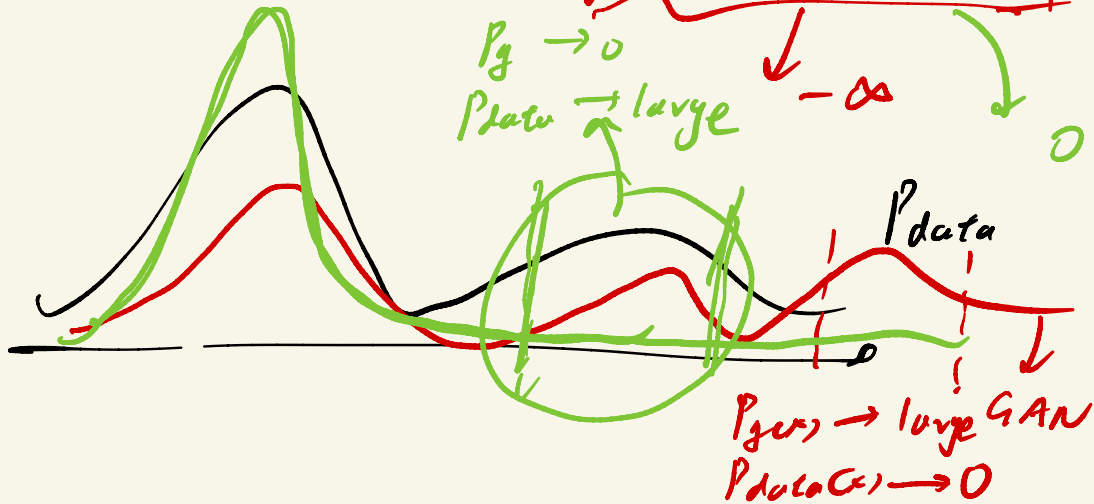
$$\log P_g(x) \rightarrow -\infty$$

GAN:

$$\int P_g(x) \log$$

$$KL(P_g \parallel P_{data}) = \int P_g(x) \log P_g(x)$$

$$- \int P_g(x) \log P_{data}(x)$$



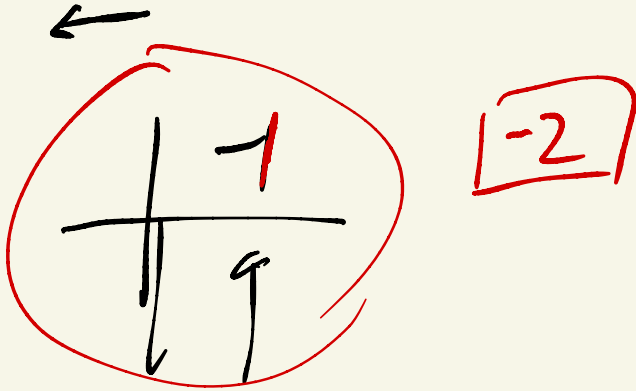
$$KL(P_y || P_{data}) + KL(P_{data} || P_y)$$

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$$\boxed{JSD(P_{data} || P_y)}$$

symmetric

---



$$r_0 + r_1 + r_2 + r_3 \dots$$

$r \rightarrow$  reward

$$r_0 + \left[ \gamma r_1 + \gamma^2 r_2 + \dots \right]$$

$$R(s_t) + \gamma \sum_{s, \epsilon} P(s, \epsilon | s_t, \pi(s_t)) V^\pi(s, \epsilon)$$

$$\underbrace{V^\pi(s)}_{\downarrow}$$

$|s|$