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COMP 5212
Machine Learning
Lecture 10

Unsupervised Learning: Clustering, Expectation Maximization

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Review: MLE vs. MAP

Maximum Likelihood estimation (MLE)

Choose value that maximizes the probability of observed data

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D|\theta)$$

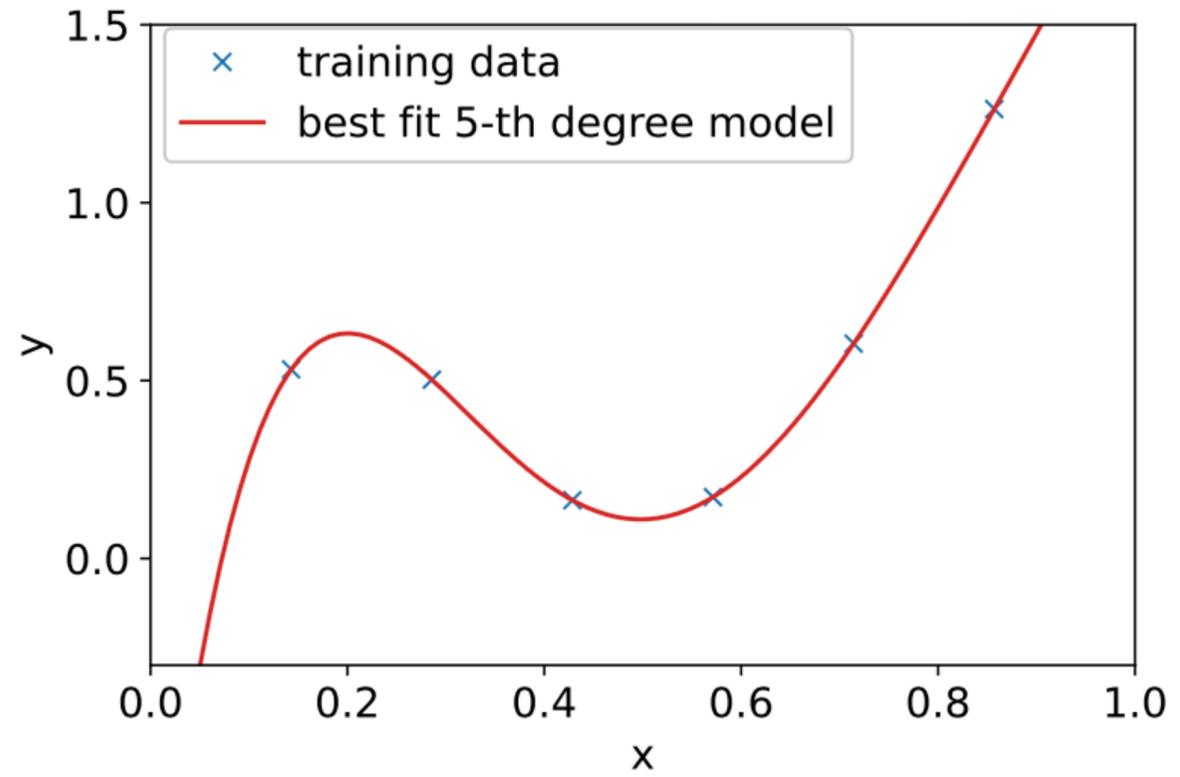
Maximum *a posteriori* (MAP) estimation

Choose value that is most probable given observed data and prior belief

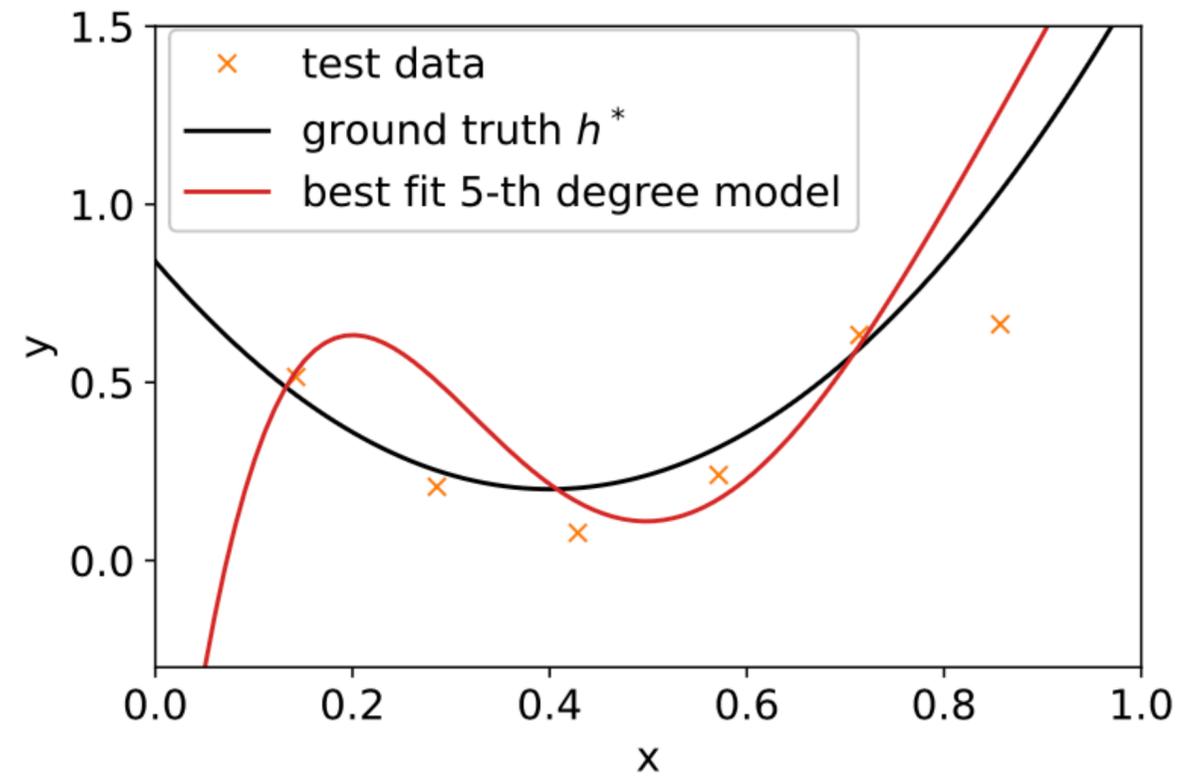
$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta|D) \\ &= \arg \max_{\theta} P(D|\theta)P(\theta)\end{aligned}$$

When are they the same?

Recap: Generalization



Zero training error



Large test error

Train, Validation, Test

Validation dataset is another set of pairs $\{(\hat{x}^{(1)}, \hat{y}^{(1)}), \dots, (\hat{x}^{(m)}, \hat{y}^{(m)})\}$

Does not overlap with training dataset

Test dataset is another set of pairs $\{(\tilde{x}^{(1)}, \tilde{y}^{(1)}), \dots, (\tilde{x}^{(L)}, \tilde{y}^{(L)})\}$

Does not overlap with training and validation dataset

Completely unseen before deployment

Realistic setting

Validation is Very Important

- Track underfitting/overfitting (in case of iterative training)
- Decide when to stop training
- Select hyperparameters

Hyperparameter tuning

When you tune hyperparameters harder, it is more likely the validation error would mismatch the test error, because you are overfitting on the validation

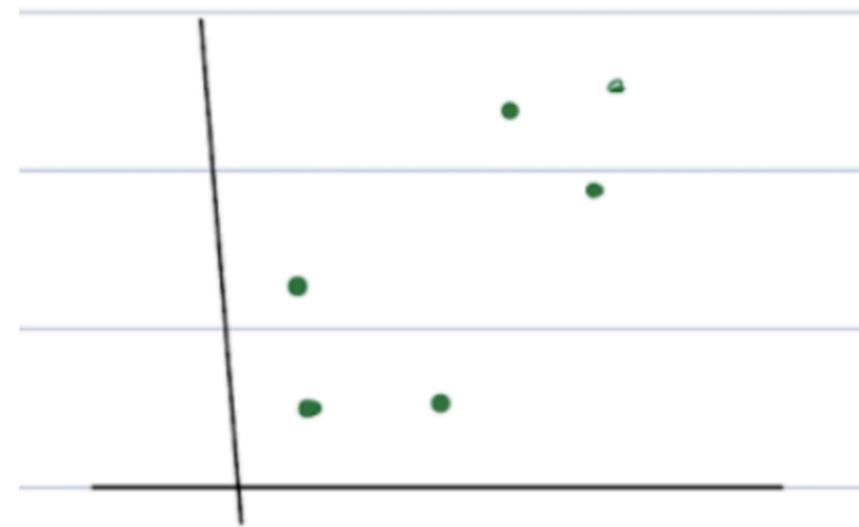
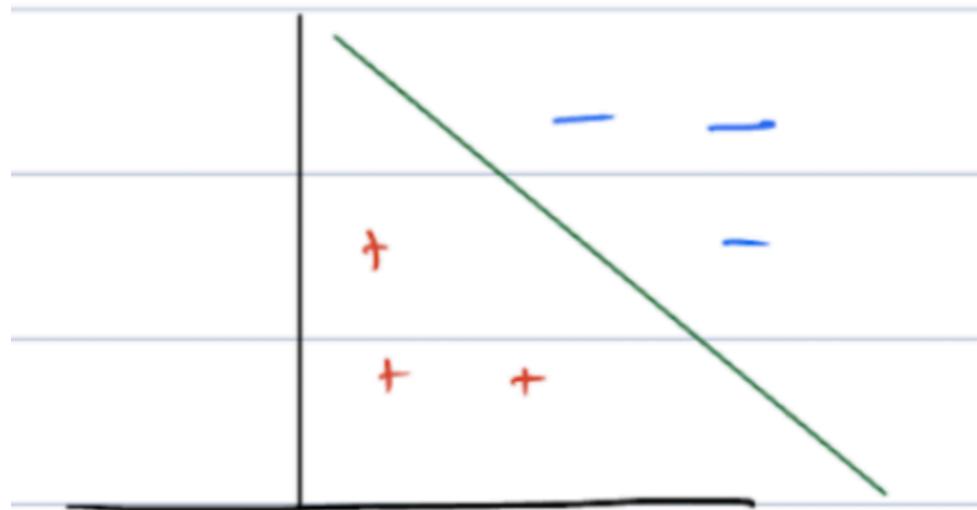
Hyperparameter tuning is a form of training

Good ML Practice

- Do not look at or evaluate on the test dataset
Many people are implicitly using test dataset as validation
- Always track the training and validation metrics/errors/losses

Unsupervised Learning

No labels, only x is given

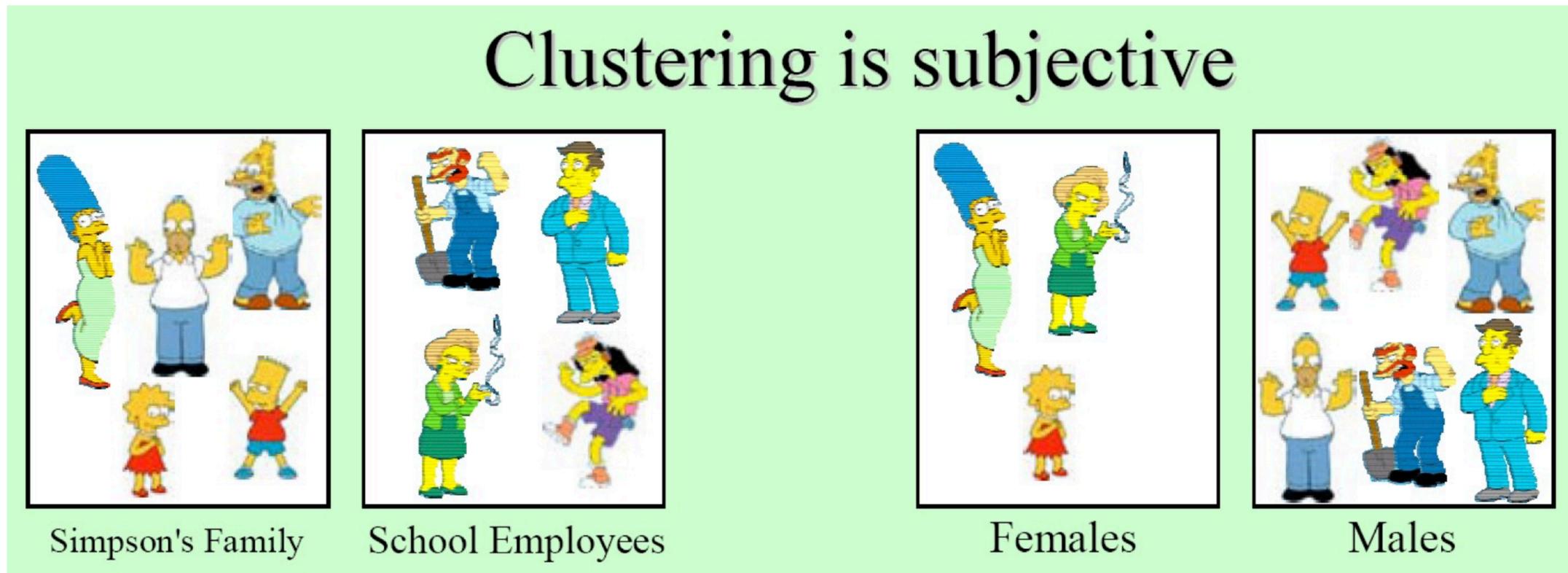


Unsupervised learning is typically “harder” than supervised learning

What is Clustering

Clustering: the process of grouping a set of objects into classes of similar objects

- high intra-class similarity
- low inter-class similarity
- It is the most common form of **unsupervised learning** **Similarity is subjective**



Distance Metrics

$$x = (x_1, x_2, \dots, x_p)$$

$$y = (y_1, y_2, \dots, y_p)$$

Euclidean distance

$$d(x, y) = \sqrt{\sum_{i=1}^p |x_i - y_i|^2}$$

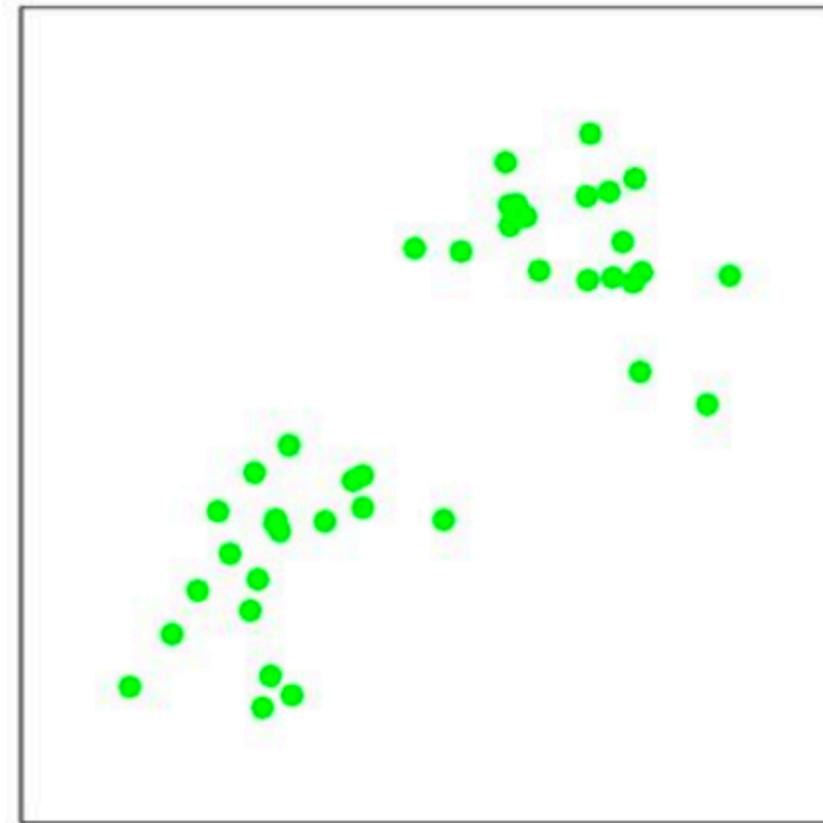
Manhattan distance

$$d(x, y) = \sum_{i=1}^p |x_i - y_i|$$

Sup-distance

$$d(x, y) = \max_{1 \leq i \leq p} |x_i - y_i|$$

K-Means Clustering



K-Means

Algorithm

Input – Desired number of clusters, k

Initialize – the k cluster centers (randomly if necessary)

Iterate –

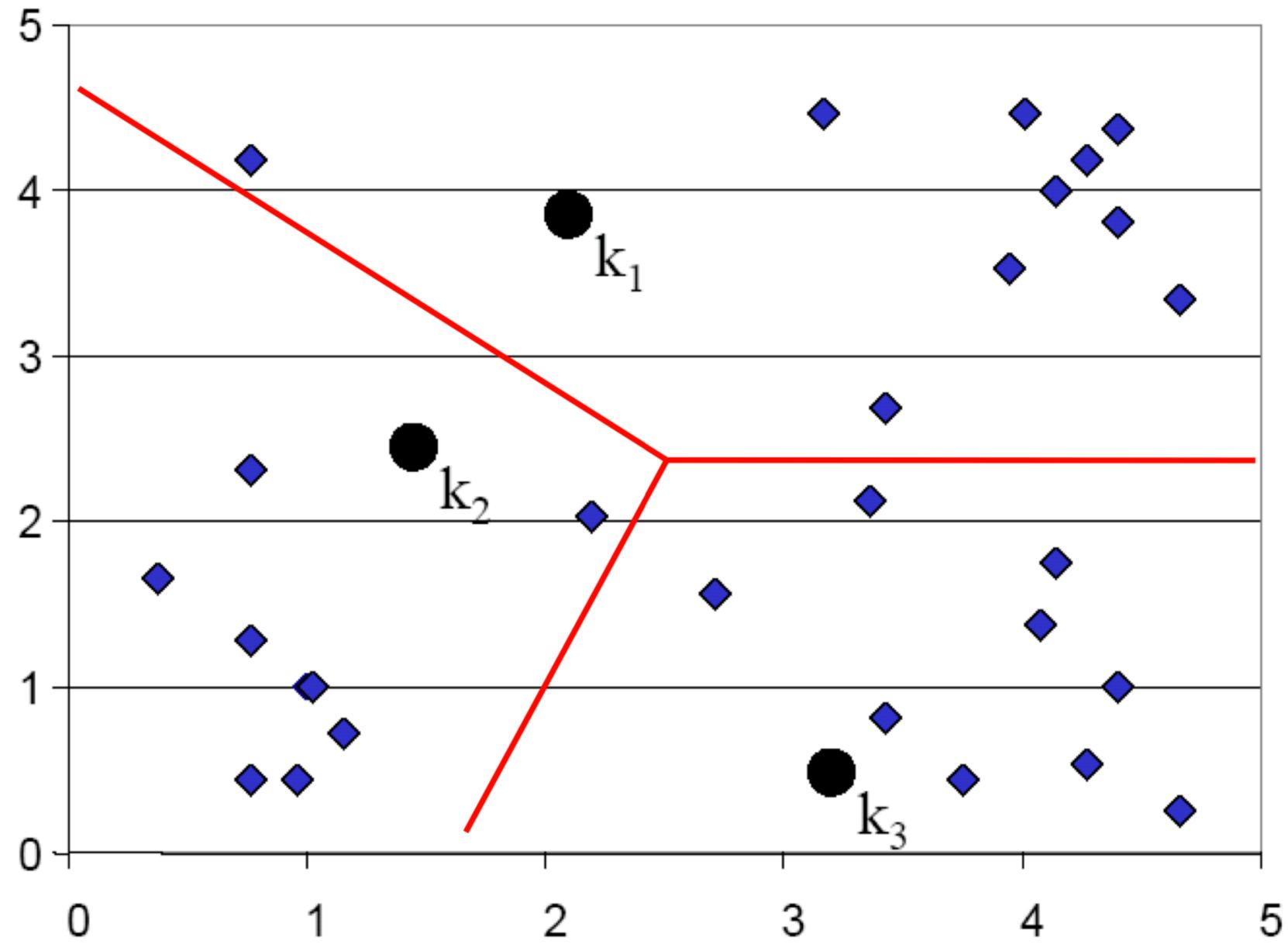
1. Assign points to the nearest cluster centers
2. Re-estimate the k cluster centers (aka the **centroid** or **mean**), by assuming the memberships found above are correct.

$$\vec{\mu}_k = \frac{1}{C_k} \sum_{i \in C_k} \vec{x}_i$$

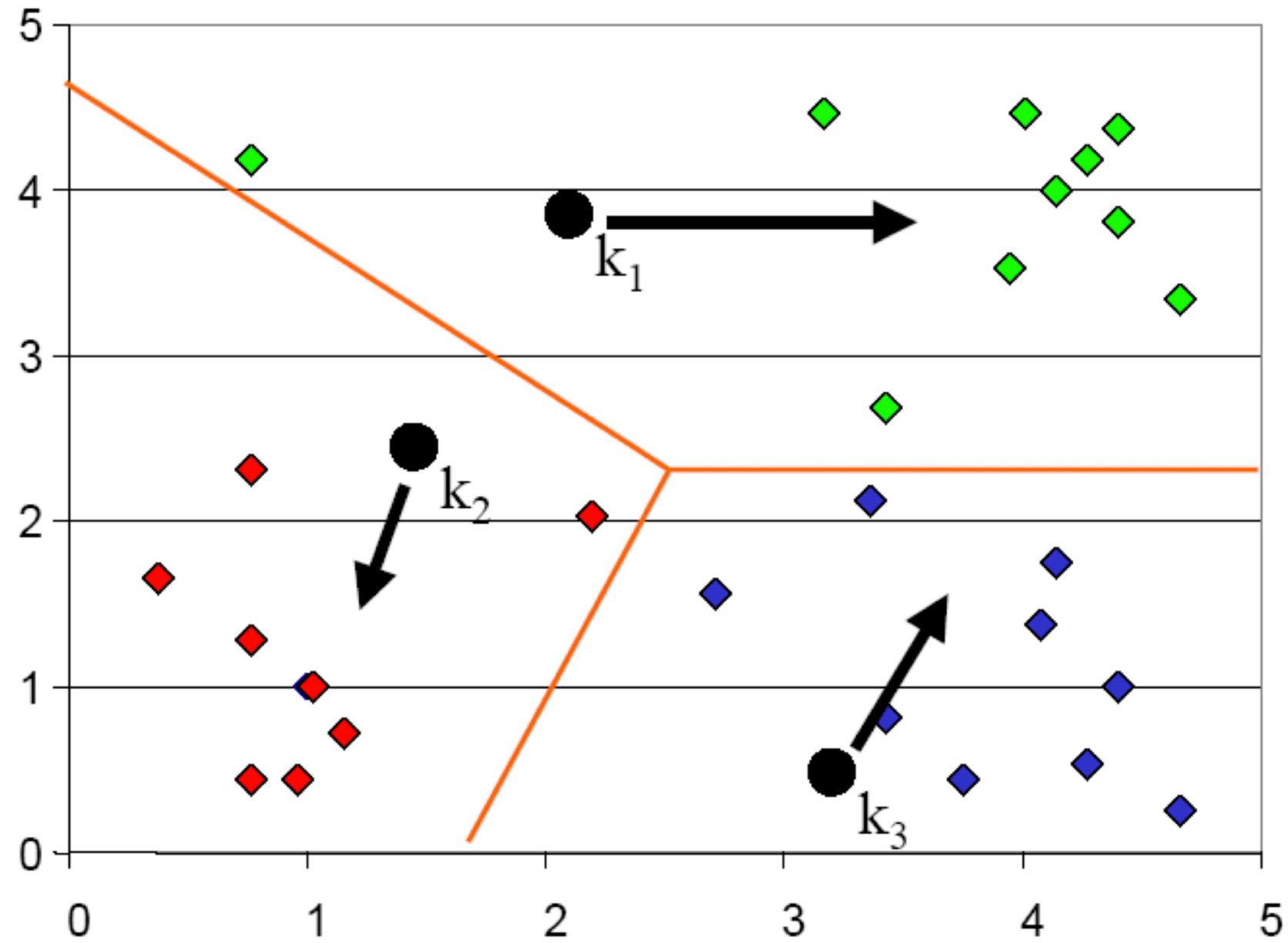
Termination –

If none of the objects changed membership in the last iteration, exit.
Otherwise go to 1.

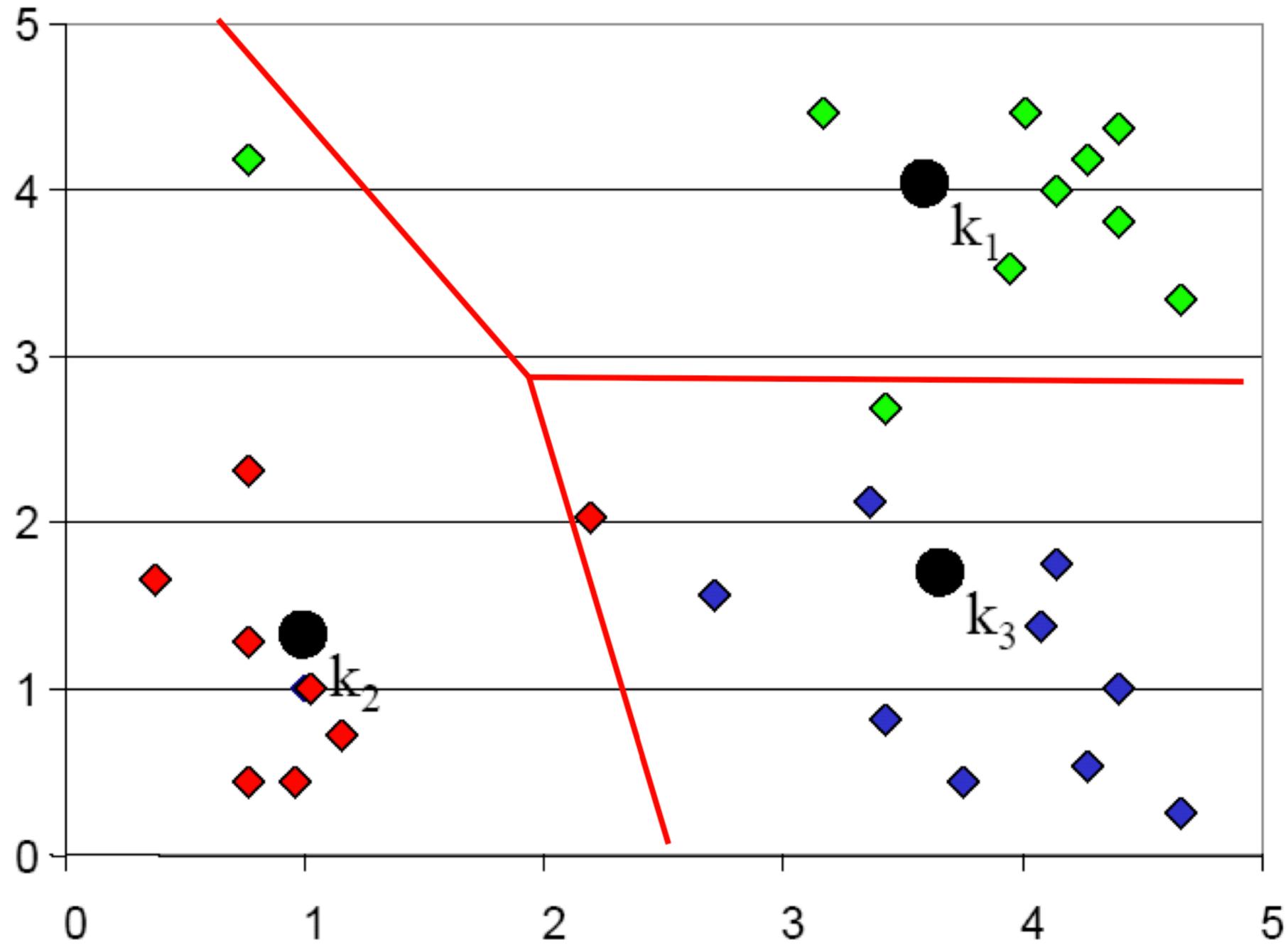
K-Means: Step 1



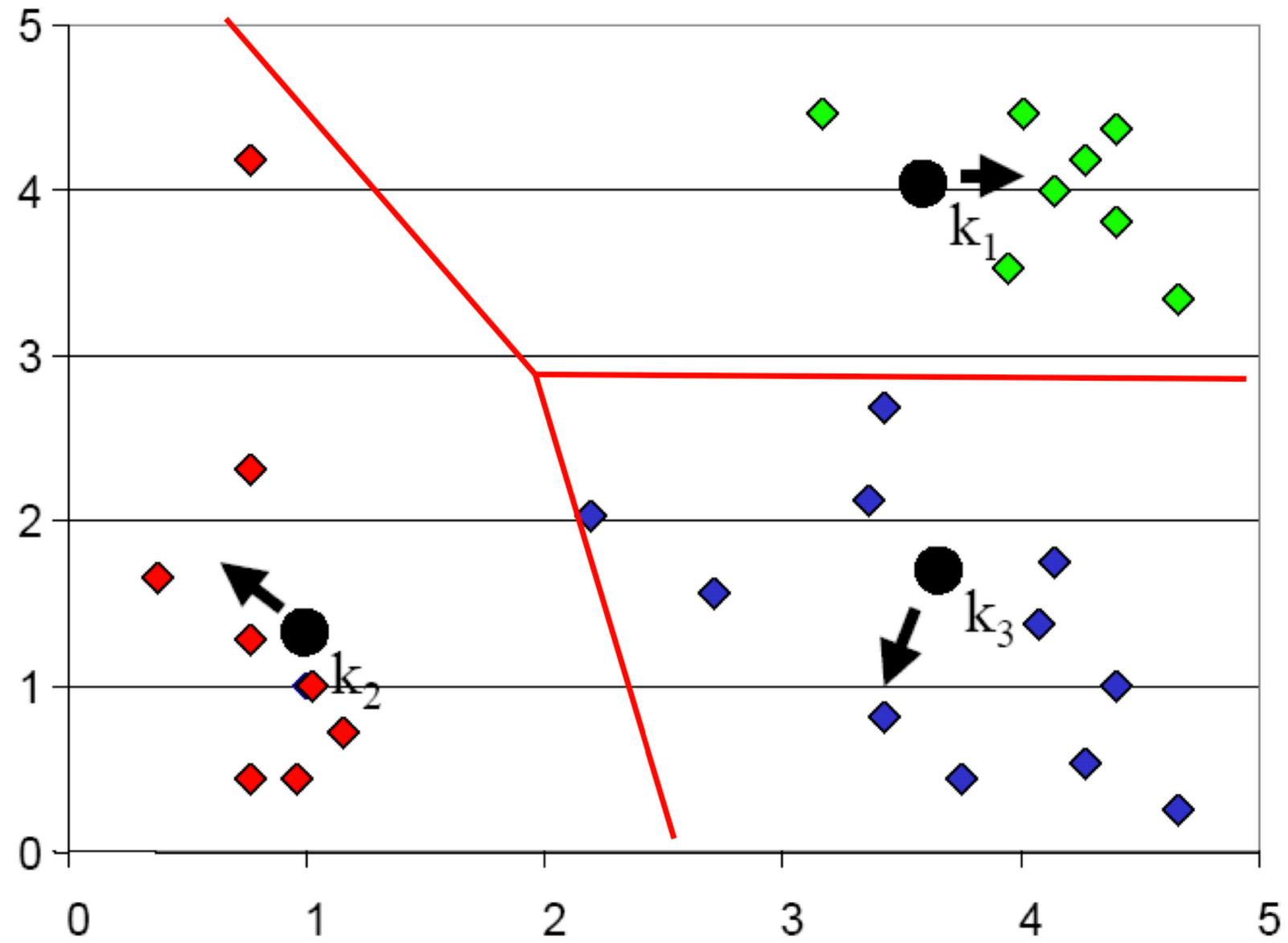
K-Means: Step 2



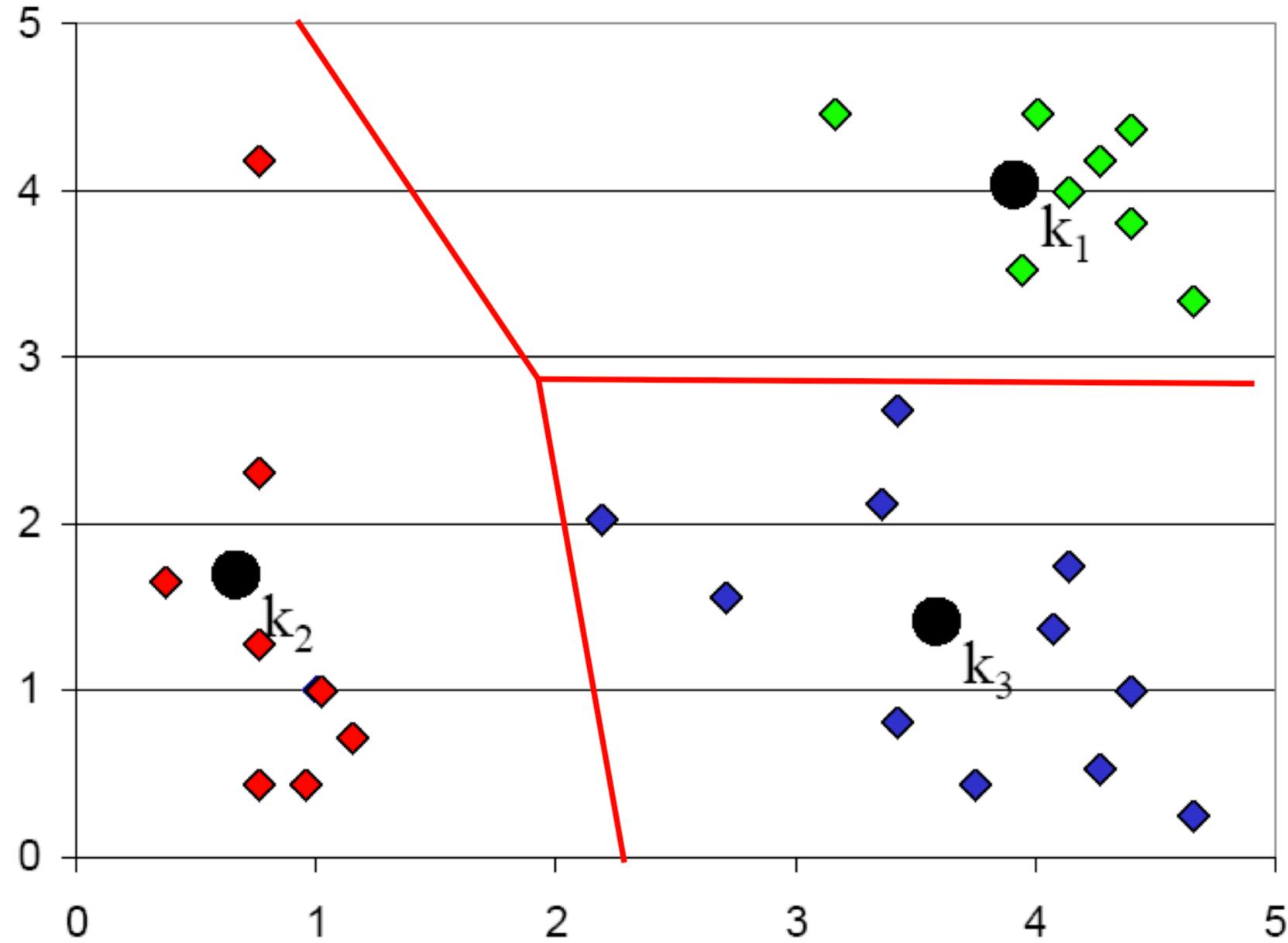
K-Means: Step 3



K-Means: Step 4



K-Means: Step 5



Objective of K-Means

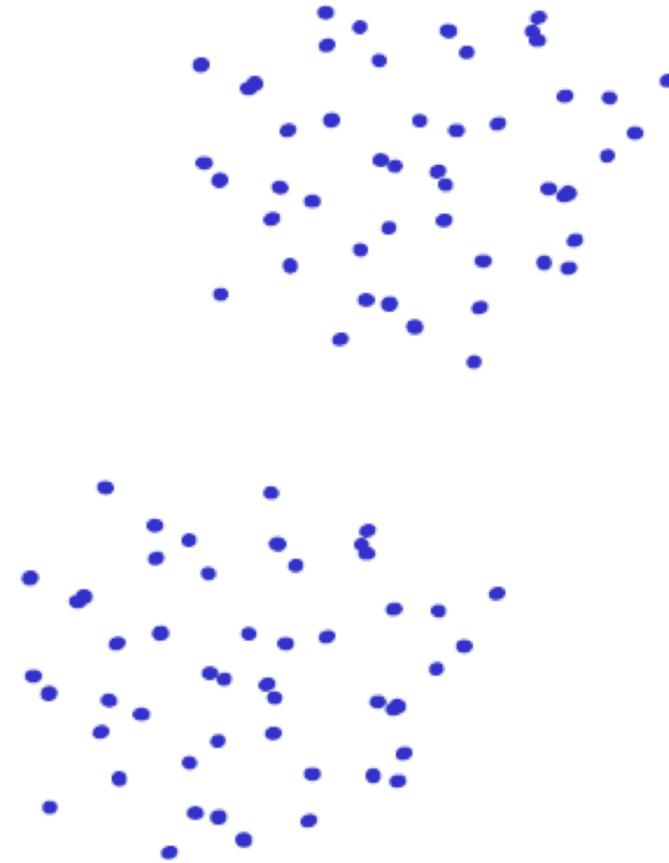
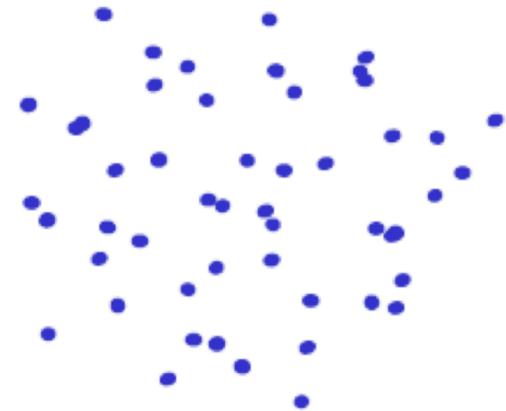
$$J(C, \mu) = \sum_{i=1}^n \|x^{(i)} - \mu^{C^{(i)}}\|^2 \text{ decreases monotonically.}$$

Proof?

K-means does not find a global minimum in this objective (it is NP-Hard)

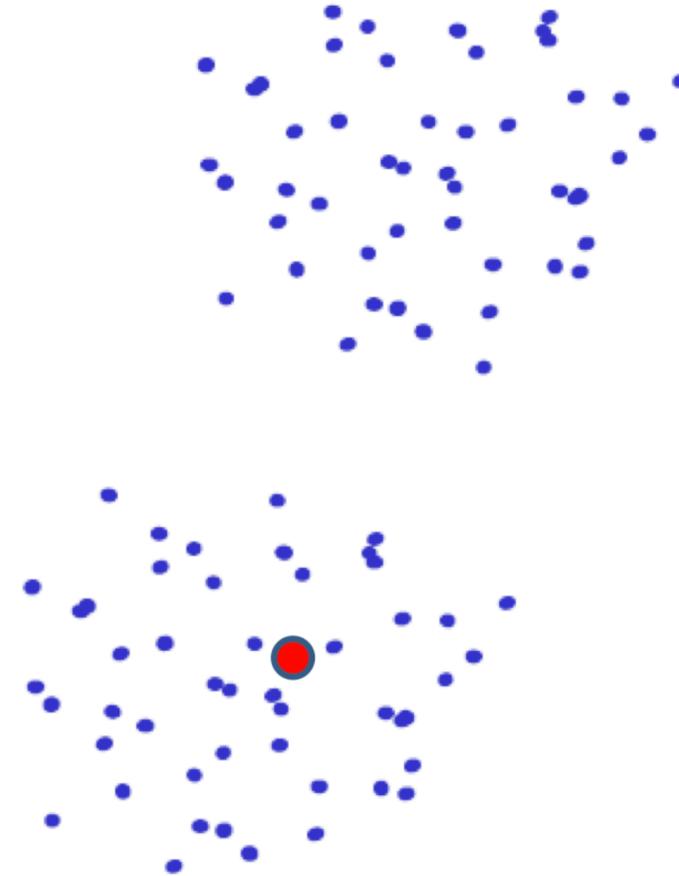
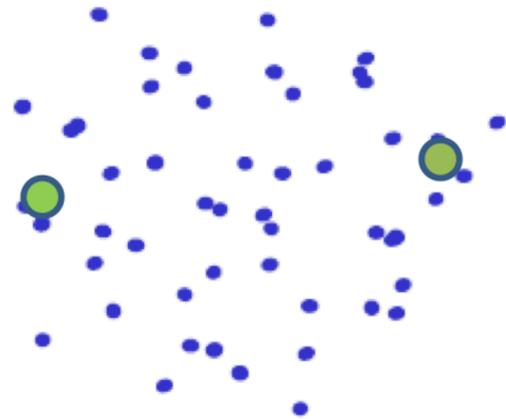
Initialization of Centers

Results are sensitive to the initialization



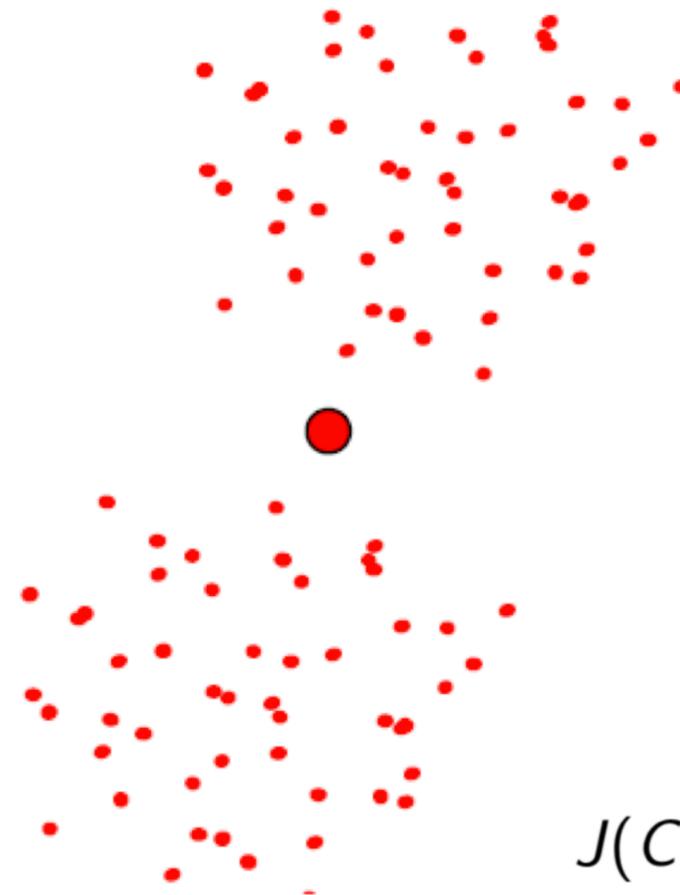
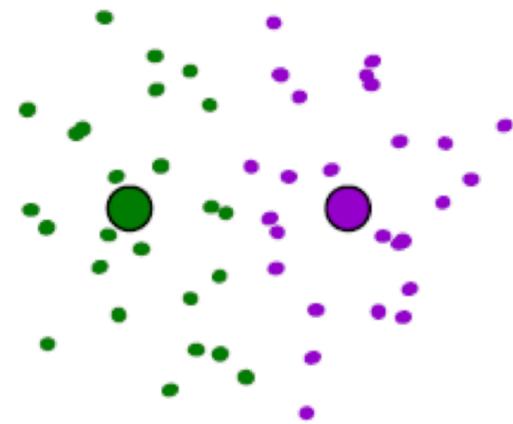
Initialization of Centers

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Initialization of Centers

Results are sensitive to the initialization



$$J(C, \mu) = \sum_{i=1}^n \|x^{(i)} - \mu^{C^{(i)}}\|^2$$

1. Try out multiple starting points and compare the objective
2. K-means++ algorithm improves the initialization

Model Selection of K-Means (or Unsupervised Learning in General)

Try out multiple starting points and compare the objective

$$J(C, \mu) = \sum_{i=1}^n \|x^{(i)} - \mu^{C^{(i)}}\|^2$$

This is unsupervised metric

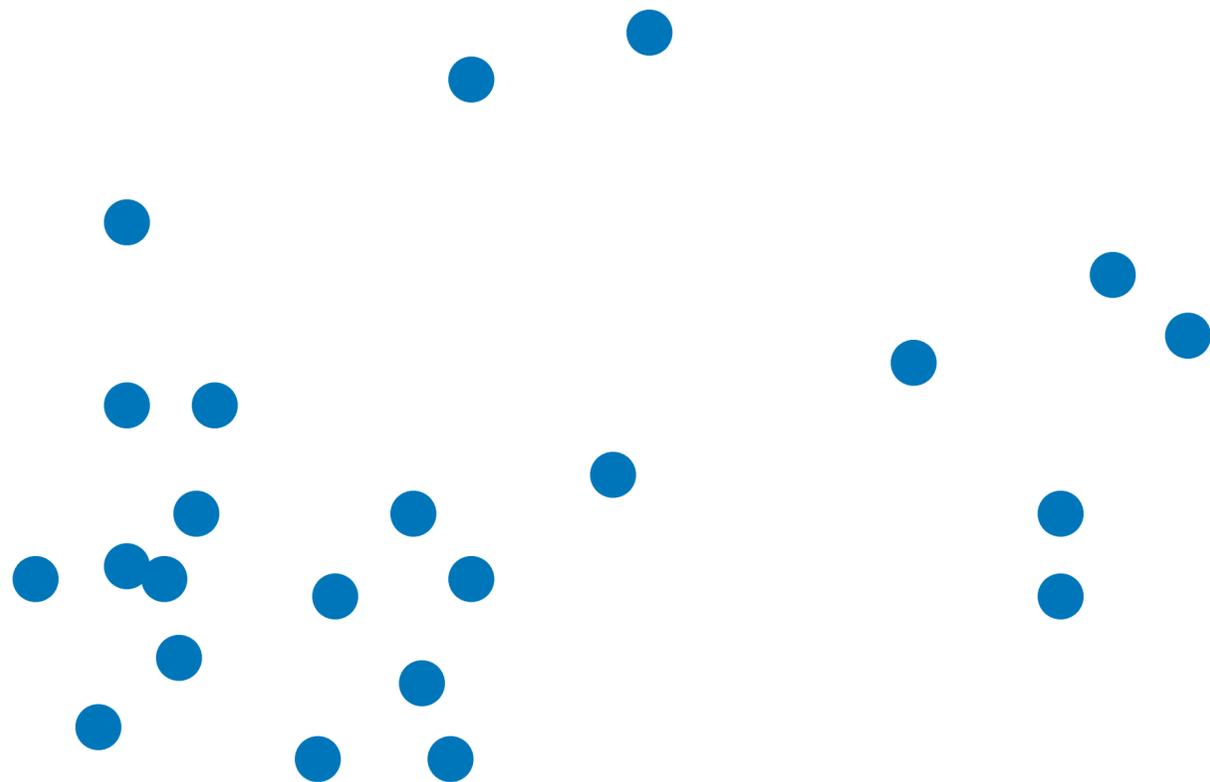
Sometimes people use supervised metrics for validation, which is not strictly unsupervised learning

1. Compute the metric on training set or test set?
2. For unsupervised learning, what is the difference of train and test?
3. Is it reasonable to assume the test input (x) is given?
4. If now I give you some data examples, ask you to cluster them. Are these data training or test?

Expectation Maximization (EM)

EM for Gaussian Mixture Model

Given a training set $\{x^{(1)}, \dots, x^{(n)}\}$ **No Labels**



We have discussed the supervised case in Gaussian Discriminative Model

Modeling data distribution is a fundamental goal in ML, not necessarily for classification

The Generative Model

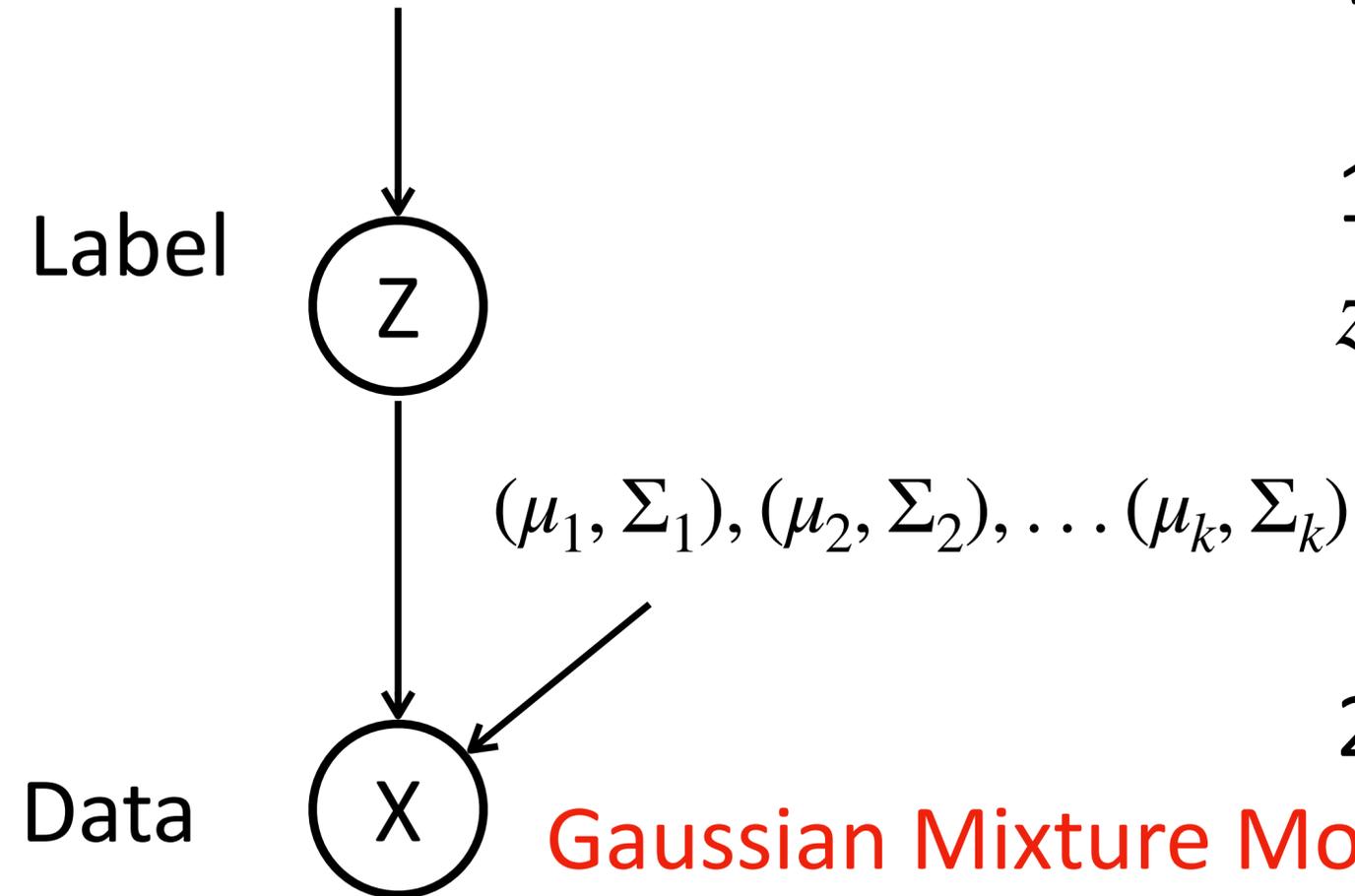
$p(z)$: multinomial, k classes (e.g. uniform)

K is a hyperparameter based on our assumption

We assume the generative process as:

1. For each data point, sample its label z_i from $p(z)$

2. Sample $x_i \sim N(\mu_{z_i}, \Sigma_{z_i})$



Gaussian Mixture Model (GMM)

Same as Gaussian Discriminative Analysis, but Z is observed in GDA

Recap: How did we do in GDA?

Binary classification: $y \in \{0,1\}, x \in R^d$

Assumption

$$y \sim \text{Bernoulli}(\phi)$$

$$x|y=0 \sim \mathcal{N}(\mu_0, \Sigma)$$

$$x|y=1 \sim \mathcal{N}(\mu_1, \Sigma)$$

$$p(y) = \phi^y (1 - \phi)^{1-y}$$

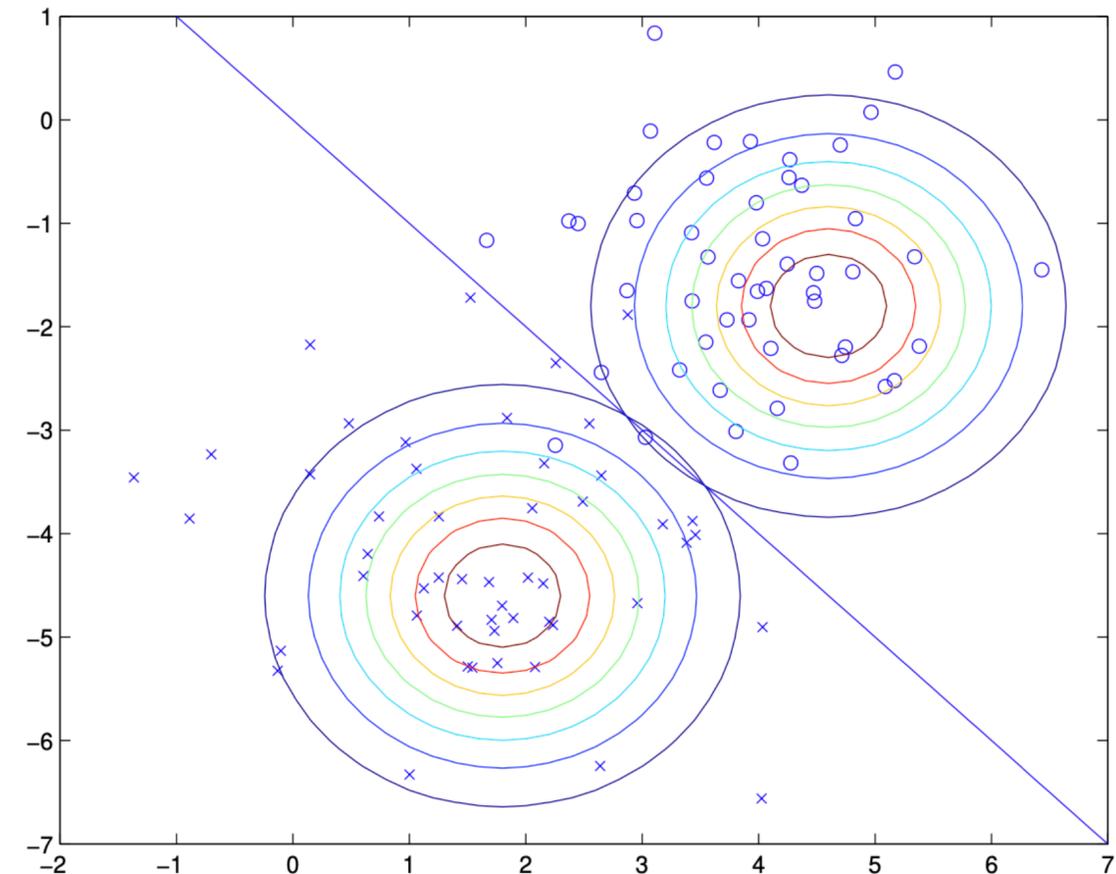
$$p(x|y=0) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu_0)^T \Sigma^{-1} (x - \mu_0)\right)$$

$$p(x|y=1) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu_1)^T \Sigma^{-1} (x - \mu_1)\right)$$

Recap: How did we do in GDA?

$$\begin{aligned}\ell(\phi, \mu_0, \mu_1, \Sigma) &= \log \prod_{i=1}^n p(x^{(i)}, y^{(i)}; \phi, \mu_0, \mu_1, \Sigma) \\ &= \log \prod_{i=1}^n p(x^{(i)} | y^{(i)}; \mu_0, \mu_1, \Sigma) p(y^{(i)}; \phi).\end{aligned}$$

$$\begin{aligned}\phi &= \frac{1}{n} \sum_{i=1}^n 1\{y^{(i)} = 1\} \\ \mu_0 &= \frac{\sum_{i=1}^n 1\{y^{(i)} = 0\} x^{(i)}}{\sum_{i=1}^n 1\{y^{(i)} = 0\}} \\ \mu_1 &= \frac{\sum_{i=1}^n 1\{y^{(i)} = 1\} x^{(i)}}{\sum_{i=1}^n 1\{y^{(i)} = 1\}} \\ \Sigma &= \frac{1}{n} \sum_{i=1}^n (x^{(i)} - \mu_{y^{(i)}})(x^{(i)} - \mu_{y^{(i)}})^T\end{aligned}$$



The Generative Model

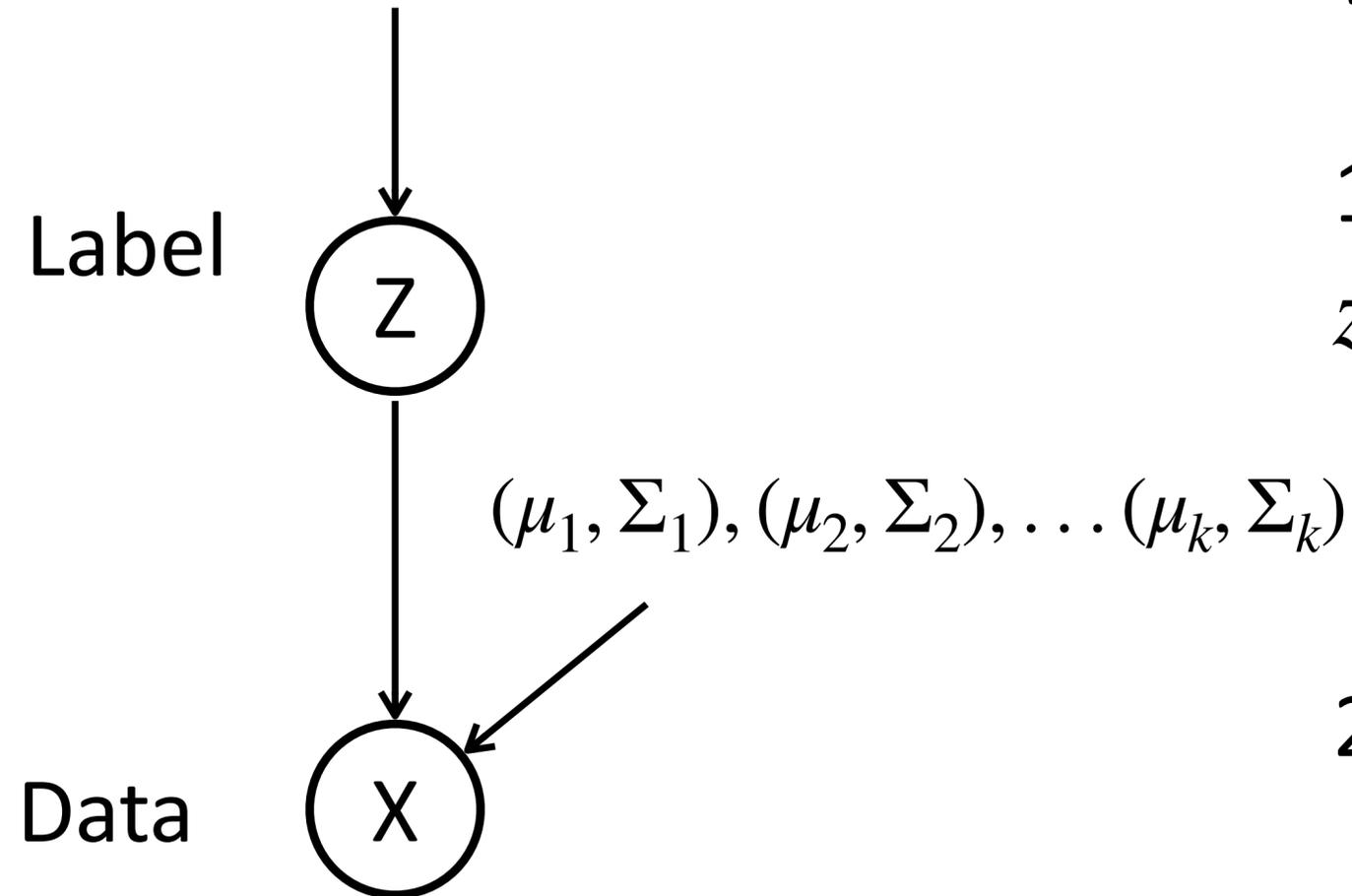
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Same as Gaussian Discriminative Analysis, but Z is observed in GDA

Maximum Likelihood Estimation for GMM

Modeling data distribution is a fundamental goal in ML

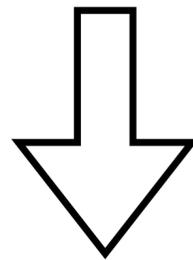
Supervised:

$$\operatorname{argmax}_{\phi, \mu, \Sigma} \log p(x, z)$$

Unsupervised:

$$\operatorname{argmax}_{\phi, \mu, \Sigma} \log p(x)$$

How to compute this?



Prediction:

$$p(z | x) \propto p(z)p(x | z)$$

Maximum Likelihood Estimation for GMM

$$\begin{aligned}\ell(\phi, \mu, \Sigma) &= \sum_{i=1}^n \log p(x^{(i)}; \phi, \mu, \Sigma) \\ &= \sum_{i=1}^n \log \sum_{z^{(i)}=1}^k p(x^{(i)} | z^{(i)}; \mu, \Sigma) p(z^{(i)}; \phi).\end{aligned}$$

1. Intractable (no closed-form for the solution)
2. Expensive when k is large (if you want to do gradient descent)

Things are easy when we know z .

In case we know z

$$\ell(\phi, \mu, \Sigma) = \sum_{i=1}^n \log p(x^{(i)} | z^{(i)}; \mu, \Sigma) + \log p(z^{(i)}; \phi).$$

$$\phi_j = \frac{1}{n} \sum_{i=1}^n 1\{z^{(i)} = j\},$$

$$\mu_j = \frac{\sum_{i=1}^n 1\{z^{(i)} = j\} x^{(i)}}{\sum_{i=1}^n 1\{z^{(i)} = j\}},$$

$$\Sigma_j = \frac{\sum_{i=1}^n 1\{z^{(i)} = j\} (x^{(i)} - \mu_j)(x^{(i)} - \mu_j)^T}{\sum_{i=1}^n 1\{z^{(i)} = j\}}.$$

Expectation maximization is to infer the latent variables first (z here), and maximize the likelihood given the inferred z

Expectation Maximization for GMM

Repeat until convergence:

{

No parameter change in E-step

(E-step) For each i, j , set

$$w_j^{(i)} := p(z^{(i)} = j | x^{(i)}; \phi, \mu, \Sigma)$$

Compute the posterior distribution,
given current parameters

(M-step) Update the parameters:

$$\phi_j := \frac{1}{n} \sum_{i=1}^n w_j^{(i)},$$

$$\mu_j := \frac{\sum_{i=1}^n w_j^{(i)} x^{(i)}}{\sum_{i=1}^n w_j^{(i)}},$$

$$\Sigma_j := \frac{\sum_{i=1}^n w_j^{(i)} (x^{(i)} - \mu_j)(x^{(i)} - \mu_j)^T}{\sum_{i=1}^n w_j^{(i)}}$$

update parameters using current $p(z | x)$

}

Expectation Maximization

- Why does it work?
- What is its relation to MLE estimation?
- How is convergence guaranteed?
- When we perform EM, what is the real objective that we are optimizing?

General EM Algorithm

$$p(x; \theta) = \sum_z p(x, z; \theta)$$

$$\begin{aligned} \ell(\theta) &= \sum_{i=1}^n \log p(x^{(i)}; \theta) \\ &= \sum_{i=1}^n \log \sum_{z^{(i)}} p(x^{(i)}, z^{(i)}; \theta). \end{aligned}$$

Let Q to be a distribution over z

This lower bound holds for any $Q(z)$

$$\begin{aligned} \log p(x; \theta) &= \log \sum_z p(x, z; \theta) \\ &= \log \sum_z Q(z) \frac{p(x, z; \theta)}{Q(z)} \\ &\geq \sum_z Q(z) \log \frac{p(x, z; \theta)}{Q(z)} \end{aligned}$$

Jensen inequality

Jensen Inequality

For a convex function f , and $t \in [0,1]$

$$f(tx_1 + (1-t)x_2) \leq tf(x_1) + (1-t)f(x_2)$$

In probability:

$$f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$$

If f is strictly convex, then equality holds only when X is a constant

Evidence Lower Bound (ELBO)

$$\begin{aligned}\log p(x; \theta) &= \log \sum_z p(x, z; \theta) \\ &= \log \sum_z Q(z) \frac{p(x, z; \theta)}{Q(z)} && \text{ELBO} \\ &\geq \sum_z Q(z) \log \frac{p(x, z; \theta)}{Q(z)}\end{aligned}$$

Because the log likelihood is intractable, people often optimize its lower bound instead

Why optimizing lower bound works? How to choose $Q(z)$, why we computed posterior in the E step, what is the benefit?

Thank You!
Q & A